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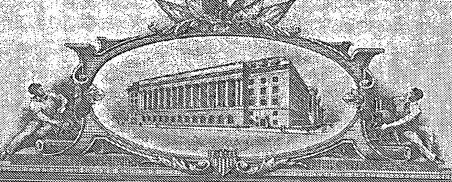
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		INVENTOR(S)			
Given Name (first and middle [if	anvi)			Residence	
Stuart M.		amily Name or Sumame		d either State or Foreign Country	
David Winters	Lindsay McMath		Burling	gton, VT	
Robert	Cowles		Hinest	ourg, VT	
Timothy C.				ırne, VT	
Mark P.	Mathew	son	Ferrist	ourgh, VT	
Walter.	Walker		Jericho	o, VT	
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PROVISIONAL APPLICATION FOR PATENT

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TITLE:

MOBILITY ASSISTANCE VEHICLE

APPLICANT:

STUART M. LINDSAY, DAVID WINTERS MCMATH,

ROBERT COWLES, TIMOTHY C. MATHEWSON AND

MARK P. WALKER

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MOBILITY ASSISTANCE VEHICLE

TECHNICAL FIELD

This invention relates to mobility assistance devices, and more particularly to a wheeled vehicle for handicapped or rehabilitating users, as well as able-bodied individuals.

BACKGROUND

Wheelchair designs provide very limited mobility when one considers the types of terrain and the varied environments which they are incapable of navigating with any sense of ease.

There are many variations and adaptations derived from the conventional design, including both three-wheeled and four-wheeled assisted mobility devices. Unfortunately, many of these designs also have significant limitations when applied to a wide range of environments and varied terrain and are limited by a combination of one or more of the following: a high risk of tipping over on uneven ground; difficulty in riding over small or moderately-sized obstacles such as ruts, stones or missing pieces of pavement; a high incidence of fatigue or strain involving the hand and wrist; an inability to be operated by a rider having limited use of one hand or arm; difficulty in mounting and dismounting the vehicle due to inherent design constrictions; awkward or inefficient steering and propulsion functions. A vehicle is desired which satisfies a number of these functional limitations.

SUMMARY

According to one aspect, the invention features a human-powered vehicle having a structural frame, two front wheels mounted to fixed axles at a forward portion of the frame for rotation, a seat secured to the frame, the seat positioned between the front wheels and adapted to pivot about a seat pivot axis, and a steerable rear wheel mounted to the frame behind the seat and defining a rear wheel kingpin axis, the rear wheel operably linked to the seat such that pivoting of the seat about the seat pivot axis causes pivoting the rear wheel about the kingpin axis to steer the vehicle.

According to another aspect, the invention features a human-powered vehicle comprising a structural frame, two front wheels mounted to a forward portion of the frame for rotation, a seat secured to the frame, the seat positioned between the front wheels and adapted to pivot about a seat pivot axis, a steerable rear wheel mounted to the frame behind the seat and defining a rear

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wheel kingpin axis, the rear wheel operably linked to the seat by a flexible chain assembly such that pivoting of the seat about the seat pivot axis causes pivoting of the rear wheel about the kingpin axis to steer the vehicle, and an actuator spring connecting the seat and the structural frame and biasing the seat toward a neutral pivot position, wherein the seat pivot axis is declined toward the front of the vehicle to define a declination angle of between about 25 and 75 degrees, wherein at least one of the two front wheels is operably connected to a hand-operable crank for propulsion of the vehicle.

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According to another aspect, the invention features a human-powered vehicle comprising a structural frame, two front wheels mounted to a forward portion of the frame for rotation, a seat secured to the frame, the seat positioned between the front wheels and adapted to pivot about a seat pivot axis, a steerable rear wheel mounted to the frame behind the seat and defining a rear wheel kingpin axis, the rear wheel operably linked to the seat by a flexible chain assembly such that pivoting of the seat about the seat pivot axis causes pivoting of the rear wheel about the kingpin axis to steer the vehicle, and an actuator spring connecting the seat and the structural frame and biasing the seat toward a neutral pivot position, wherein the seat pivot axis is substantially vertical, wherein at least one of the two front wheels is operably connected to a hand-operable crank for propulsion of the vehicle.

In one embodiment, the seat pivot axis is substantially vertical. In another embodiment, the seat pivot axis is declined toward the front of the vehicle to define a declination angle between about 25 and 75 degrees, more preferably between about 35 and 50 degrees and most preferably about 45 degrees. The seat pivots at the declination angle about at least two pivot points.

In one embodiment, at least one of the two front wheels of the vehicle is operably connected to a hand-operable crank for propulsion of the vehicle. The vehicle may include two independent by hand-operable cranks, each crank operably connected to a corresponding one of the front wheels. In another embodiment, the vehicle hand-operable cranks are adapted to be rotatable about substantially horizontal axes disposed above the front wheels. The hand-operable cranks can include crank sprockets and the front wheels include wheel sprockets, the crank sprockets being coupled to the wheel sprockets by means for positive engagement. The wheel sprockets can be coupled to the wheels by freewheel sprockets.

In another embodiment, each of the independent hand-operable cranks are adapted to drive a miter gear and each of the two front wheels are adapted to be driven by a bevel gear. The crank miter gear is coupled to the wheel hub bevel gear by a driveshaft for positive engagement. The bevel gear is attached to the front wheel hub for positive rotation of the front wheel.

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In one embodiment, the seat is operably connected to the rear wheel by a flexible chain. The chain may be trained about a drive sprocket secured to the seat and a driven sprocket secured to the wheel, the chain being crossed between the drive and the driven sprockets. The seat is operably linked to the rear wheel to define a steering ratio of between about 3:1 and 6:1, and preferably about 4.5:1.

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The vehicle may further include independent hand-operable front and rear brakes. In accordance with further embodiments of the invention, the vehicle includes an actuator connecting the seat and the structural frame and biasing the seat toward a neutral pivot position. In one embodiment, the actuator is an adjustable pressurized cylinder or spring, for example. In another embodiment, the front wheels are each mounted for rotation about a respective axle secured to the frame by a fork spanning the wheel. In another embodiment, the front wheels are each mounted for rotation about a respective cantilevered axle secured to the frame. In one embodiment, to improve stability, the front wheels are slanted toward each other to define a positive camber angle with respect to vertical. According to one embodiment, the seat is positioned such that the rear wheel carries between about 20 and 40 percent of a total combined weight of the operator and the vehicle in a static condition. In one embodiment, the front drive wheels are cambered to enhance overall stability of the vehicle.

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In accordance with one embodiment, the vehicle includes a steering assembly alignment device located beneath the seat, which includes a shaft collar affixed to the steering drive sprocket. The shaft collar is mounted upon the vertical seat post shaft, and held in position by one or more setscrews. Loosening the setscrews located within the shaft collar allows the drive sprocket to be adjusted relative to the seat post shaft, thereby adjusting alignment of the seat position relative to the position of the rear wheel.

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In accordance with further embodiments of the invention, the vehicle may include a damper connecting the rear wheel fork and the structural frame, allowing for improved steering and handling by preventing excessive rotational motion of the rear wheel fork assembly. In

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another embodiment, the damper is a bi-directional torsion spring which is fitted to the vertical steering tube and provides a dampening effect to any rotational forces.

The mobility assistance device described herein can provide a safe, efficient and improved approach to enhanced mobility under a wide range of settings and conditions. In addition, it can enable a number of rehabilitative functions, as well as providing recreational cross-training opportunities for able-bodied individuals. It is particularly useful in enhancing the mobility of users with a lower extremity disability and a moderate level of upper body strength. The modes of steering and propulsion of the vehicles can be adapted and configured to complement the unique physical capabilities of such users. In addition to enhancing the mobility of the user, the vehicles can provide therapeutic and rehabilitative benefits.

One embodiment of the invention is especially well suited for providing mobility within confined indoor spaces while still providing excellent mobility for rough or uneven outdoor terrain. One embodiment utilizes shaft-drive propulsion and a compact frame design.

The details of one or more embodiments of the invention are set forth in the accompanying drawings and the description below. Other features, objects, and advantages of the invention will be apparent from the description and drawings, and from the claims.

DESCRIPTION OF DRAWINGS

FIG 1 is a perspective view of the vehicle according to one embodiment of the invention.

FIGS. 2A and 2B depict top views of the vehicle of FIG. 1 in neutral and turned positions, respectively.

FIG. 2C is a detailed side view of the vehicle of FIG. 1, depicting the steering assembly alignment device.

FIG 2D is a detailed bottom view of the vehicle of FIG 1.

FIG 3 is a side view of the vehicle of FIG 1.

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FIG 4 is a front view of the vehicle of FIG 1.

FIG 5 is a detailed view of the rear wheel steering assembly of the vehicle of FIG 1.

FIG 6 is a perspective view of the vehicle according to another embodiment of the invention.

FIGS. 7A and 7B are top views of the vehicle of FIG. 6.

FIG 8 is a side view of the vehicle of FIG 6.

FIG 9 is a front view of the vehicle of FIG 6.

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FIG. 10 is a front view of an alternative embodiment of the vehicle of FIG. 6 where the front drive wheels are cambered to enhance stability of the vehicle.

FIGS. 11A and 11B are side views of a reverse gear drive in an engaged and disengaged position, respectively.

FIGS. 12A and 12B show detailed views of the reverse gear of FIGS. 11A and 11B.

FIG 13 shows a detailed view of components of the reverse gear drive of FIGS. 11 and 12.

FIG. 14 is a perspective view of the vehicle according to another embodiment of the invention.

FIG. 15 is a side view of the vehicle in figure 14.

FIG. 16 is a front view of the vehicle in figure 14.

FIG. 17 is a perspective view of the shaft-drive propulsion for the vehicle in figure 14.

FIG. 18 is a front view of the (right side) shaft-drive propulsion for the vehicle in figure

DETAILED DESCRIPTION

Throughout the discussion of the illustrative embodiments, it is to be understood that in the figures, like reference generally refer to like elements throughout the different views.

Referring to FIGS. 1 and 2, a vehicle 100 has a structural frame 105, two front drive wheel assemblies 110a, 110b (hereafter collectively referred to as 110), a seat 115, and a steerable rear wheel assembly 120. In one embodiment, frame 105 is of tubular construction and consists of a horizontal equilateral triangle with an extension 125 to support the rear wheel assembly 120. The two front drive wheel assemblies 110 may include front forks 130, 130b which are affixed to a forward portion of the frame 105 in front of the seat 115.

The seat 115 is rotatably mounted to the frame 105 between and aft of the two front drive wheels assemblies 110. The seat 115 is operably connected to the rear wheel assembly 120 such that rotation of the seat 115 causes rotation of the rear wheel assembly to effect steering of the vehicle 100. Advantageously, the seat 115 includes a seat base 117 and a seat back 119, the seat base declined rearward to keep the rider well positioned in the seat 115. In some embodiments, the vertical height of the seat base 117 is adjustable and the angle of inclination of the seat back

119 is adjustable. The seat may be constructed from fiberglass, metal or other substantially rigid material. Alternatively, the seat 115 is a simple platform with aluminum rails (not shown) having fabric mesh laced thereon for improved comfort on either the seat base 117 or the seat back 119. The seat 115 may include layers of foam or other resilient materials to increase rider comfort and reduce fatigue. In some embodiments, the vehicle includes a footrest 128. The footrest 128 is attached to a forward lower portion of the frame 105 between the front drive wheel assemblies110. Appropriate configured rests (not shown) may be included along the footrest 128 for receiving and retaining the feet of the rider.

The rear wheel assembly 120 may include a rear fork 132, a rear hub and rim combination 133 for supporting a rear tire 134. In one embodiment, the rear tire has a high profile for improved rider comfort and stability of the vehicle 100. The front drive wheel assemblies 110 include front drive hubs 140a, 140b, spokes 141 or other means of attaching the hub to the rim, rims 145a, 145b for supporting front tires 150a, 150b. In one embodiment, the front drive hubs 140 are conventional bicycle-style hubs as shown in FIG 1. In another embodiment, the front drive hubs 140 are a cantilever-style axle and hub combination supported by a single wheelchair-style mount 399 (FIG 14). In one embodiment, the front forks 130 are 24-inch bicycle forks and may include gussets (not shown) to add additional strength.

Advantageously, the vehicle 100 is configured to enable a user to mount and dismount the seat 115 independently or with minimal assistance. In one embodiment, the user mounts and dismounts the seat 115 from the front of the vehicle 100 between the front drive wheel assemblies 110 utilizing the foot rest 128. Mounting and dismounting the vehicle can vary according to the combined abilities and disabilities of the particular user. The overall size and configuration of the vehicle 100 may be modified to accommodate the size of the user and the intended application for the mobility device (e.g., indoor or outdoor use). In one embodiment, the seat 115 is located on the frame 105 aft of the front drive wheel assemblies 110 such that the rear tire 134 carries between about 20 and 40 percent of a total combined weight of the operator and the vehicle 100 in a static condition. The configuration of the frame 105 and the diameter of the rear wheel 120 ensures a relatively low center of gravity for enhanced stability of the vehicle 100, particularly over uneven terrain. In some embodiments the front drive wheel assemblies 110 are slanted toward each other above the frame 105 to define a positive camber angle with respect to vertical (see FIG 9) to improve overall vehicle stability.

The frame 105 may be constructed from a range of materials including for example, aluminum, steel, or steel alloy, depending on the intended application of the vehicle 100. In one embodiment, the frame 105 is constructed of primarily 1 ½-inch 4130 chrome moly tubing, which has been gas metal arc welded (MIG welded). The 4130 chrome moly tubing provides a high strength-to-weight ratio. Referring now collectively to FIGS. 2A, 2B, 3 and 4, and in one embodiment, steering of the vehicle is accomplished by rotation of the seat 115 about a substantially vertical axis 160 (FIG 4). The seat 115 is mounted to a platform 165 that is affixed to the top end of a steering support shaft 170. The seat steering support shaft 170 is rotatably affixed to the frame with a bearing assembly, such as a bicycle headset, to permit free rotation of the seat 115. A drive sprocket or chain ring 175 is affixed to the lower end of the seat support shaft 170. The rear fork 132 includes a driven rear sprocket (or pulley) 180 attached to the fork steerer tube 198 and rotatably affixed to the frame 105, with a headset or other bearing assembly. The driven rear sprocket or pulley 180 is attached to the fork steerer tube 198 below the bearing surface on the frame 105.

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In one embodiment, a chain 185 is trained around the steering drive sprocket 175 and the rear driven sprocket 180 to operably connect the seat 115 and the rear wheel assembly 120. The chain 185 may be, for example, a flexible chain, roller chain or nylon belt. Advantageously, the chain 185 is disposed about the drive sprocket 175 and the rear driven sprocket 180, crossed in a "figure-8" configuration as shown in FIGS. 1, 2A and 2B. The chain 185 can include turnbuckles 190a, 190b to enable the adjustment of the tension of the chain 185 and prevent the chain 185 from derailing from the drive sprocket 175 and rear driven sprocket 180. In some embodiments, the relative position of the drive sprocket 175 can be adjusted to properly establish the chain line between the drive sprocket 175 and the rear driven sprocket 180.

Referring to FIG 2C, one embodiment of the vehicle 100 includes a steering assembly alignment device 191 located beneath the seat 115, which includes a shaft collar 192 affixed to the steering drive sprocket 175. The shaft collar 192 is disposed upon the seat steering support shaft 170 and held in position by set screws 194.

Loosening the set screws 194 located within the shaft collar 192 allows the drive sprocket 175 to be adjusted relative to the seat steering post shaft 170, thereby adjusting alignment of the seat position relative to the position of the rear wheel assembly 120.

Referring to FIG 2D, and in one embodiment, the seat steering assembly 114, comprised of the seat 115, seat plate 165, seat steering support shaft 170, actuator 195, drive sprocket 175, steering shaft collar 192 and steering shaft collar set screw 194, includes at least one actuator 195 disposed between the platform 165 at a first end and the frame 105 at a second end. When the seat 115 is rotated for turning the vehicle 100, the actuator 195 is biased toward returning the seat 115 and consequently the rear wheel assembly 120 toward a centered, straight-ahead position. The actuator 195 may be a pre-tensioned adjustable spring, an adjustable pressurized cylinder, or a similar biasing device. In one embodiment, the actuator 195 is adjusted to accommodate, for example, the weight of the rider and the intended use of the vehicle 100.

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In operation, when the rider rotates the seat 115 in one direction, the crossed chain 185 rotates the rear wheel assembly 120 in an opposite direction, but the vehicle turns in a direction corresponding to the direction of rotation of the seat 115. As shown in FIG 2B, rotating the seat 115 toward the right, results in a rotation of the rear wheel assembly 120 toward the left. This results in the vehicle 100 turning to the right, corresponding to the direction of rotation of the seat 115.

Referring to FIG. 5, in one embodiment, the vehicle may include a damper 197 connecting the rear wheel fork 132 and the structural frame 105, allowing for improved steering and handling by preventing excessive rotational motion of the rear wheel fork 132 assembly. In one embodiment, the damper 197 is a bi-directional torsion spring which is fitted to the vertical steering tube 198 and provides a dampening effect to any rotational forces.

Referring now to FIG. 6, in a second embodiment, steering of the vehicle 100 is accomplished by rotation of the seat 115 about a seat pivot axis 200, which is declined toward the front of the vehicle 100 to define a declination angle D. The declination angle D is preferably between about 25 degrees and 75 degrees, more preferably between about 35 degrees and 50 degrees and most preferably about 45 degrees. In one embodiment, the seat 115 is suspended on and rotates about an upper pivot attachment point 205 and a lower pivot attachment point 210 positioned along the seat pivot axis 200.

The upper attachment point 205 is mounted high on the seat back 119 and the lower pivot attachment point is mounted in a frontward portion of the seat base 117. As the angle of rotation of the seat 115 is not substantially parallel to the angle of rotation of the rear wheel assembly 120, as previously described with reference to FIGS. 1 to 2C, a modified steering linkage is

utilized. A chain 215 is trained about the rear sprocket 180 of the rear wheel assembly 120. Two steering cables 220a, 220b attached to each end of the chain 215 at turnbuckles 190a, 190b operably connect the rear sprocket 180 of the rear wheel assembly 120 to the seat 115 at cable attachment points 225a, 225b. In one embodiment, the steering cables 220 are aircraft cables having swaged ends for attachment to the turnbuckles 190 and the seat 115.

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Advantageously, the chain 215 is crossed about the rear sprocket 180 in a "figure-8" configuration as shown in FIGS. 6, 7A and 7B. The turnbuckles also provide adjustability of tension of the chain 215 about the rear sprocket 180. With renewed reference to FIG 6, the steering cables 220 are redirected from a substantially horizontal orientation to a substantially vertical orientation for attachment to the seat 115 at attachment points 225a, 225b through guides 230a, 230b. The guides 230 are affixed to the frame 105.

Referring now collectively to FIGS. 6, 7A-7B, 8 and 9, in operation, when the rider leans to turn the seat 115 in one direction, the chain 215 rotates the rear wheel assembly 120 in an opposite direction, but the vehicle turns in a direction corresponding to the direction of rotation of the seat 115. As shown in FIG 7B, rotating the seat back 119 toward the left results in a rotation of the rear wheel assembly 120 toward the right. This results in the vehicle 100 turning to the left. This left turn is initiated by the rider leaning to the left with the upper torso, which results in the seat base 117 rotating to the right. This steering configuration allows the rider to lean into turns and improves overall maneuverability and stability of the vehicle 100. According to one embodiment, the ratio between the diameter of the rear sprocket 180 and the distance between attachment points S is selected such that, the seat 115 rotates in the direction of arrows 235 about 10 degrees to the left and right to achieve a full range of steering of the vehicle 100.

Referring now to FIGS. 1 and 10, in one embodiment, the vehicle 100 includes two independent hand-operable cranks 250a, 250b operably connected to a corresponding front drive wheel assembly 110 for propulsion of the vehicle 100. The cranks 250 include crank sprocket 255a, 255b, crank arms 260a, 260b and handle 265a, 265b rotatably mounted to the crank arms 260. In one embodiment, the crank sprockets 255 are conventional bicycle chain rings, the crank arms 260 are a bicycle pedal crank and the handles 265 are a modified pedal bolt surrounded with a padded sleeve for comfort and grip. The crank sprockets 255 are coupled to front wheel sprockets 270a, 270b by front drive chains 275a, 275b. The chains 275 are roller chains, toothed nylon belts, or similar flexible connecting means. In one embodiment, the crank sprockets 255

are each a 28-tooth chain ring and the front wheel sprockets 270 are each a 32-tooth chain ring. The front wheel sprockets 270 are coupled to front wheel drive hubs 140.

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In operation, rotating the handles 265 in a first direction, rotates the front drive wheel assembly 110 and the vehicle 100 in a forward direction. Advantageously, the front wheel sprockets 270 may be freewheel sprockets, which allow the rider to pedal the vehicle 100 forward and coast if not pedaling. Also, by employing freewheel sprockets, the handles 265 can be rotated in a second direction to position the handles 265 for maximum leverage when, for example, starting the vehicle 100 from a stationary position. Tension in the front drive chains 275 is maintained and adjusted by changing the height of the hand operable crank assemblies 250 disposed over the front fork steerer tubes 280a, 280b. The position of the adjustable crank assembly is held in place over the front fork steering tubes 280 by two pinch bolts, for example (not shown). Different lengths of the crank arms 260, varying configuration of handles 265, and crank sprocket 255 to front wheel sprockets 270 ratios are all contemplated by the invention to suit particular applications.

In one embodiment, the vehicle 100 may include a reverse gear drive 300 as depicted in FIGS. 11A, 11B, 12A, 12B and 13. The drive 300 is attached to one or both adjustable crank assemblies 250 above the front drive wheel assemblies 110. The circumferential surface of a reverse roller 305 is scored or knurled for direct positive engagement with the front tires 150. The reverse direction is denoted by the arrow 307 and the direction of reverse rotation is denoted by the arrow 309. The reverse cog 310 is positioned for engagement of the chain 275 against upper and lower jockey rollers 317, 319. The reverse drive 300 includes a reverse roller 305 (FIG.13) joined to a freewheeling reverse cog 310 which is rotatably attached to the bracket 315 is attached rotatably to a pivot 320. A clamp handle 325 is rotatably attached to the bracket 315 via a first lever 335 and a second lever 340. In one embodiment, the clamp 325 of the reverse gear drive 300 is a Destaco-type clamp which simultaneously locks the reverse roller 305 into position for engagement with the front tires 150 and the reverse cog 310 into position for engagement with the front drive chain 275 until manually released. Other suitable clamp devices are contemplated.

In operation, movement of the clamp handle 325 in the direction of the arrow 327 (FIG. 11B and 13) displaces the first and second levers 335, 340 thereby rotating bracket 315 about the pivot 320 and engaging the reverse roller 305 with the front tire 150 and engaging the reverse

cog 310 with the chain 275b. With the reverse drive 300 engaged, rotation of the crank 260 in the direction of the arrow 345 rotates the reverse cog 310 and the reverse roller 305 for rotation of the front drive wheels 110 in the direction necessary for rearward propulsion of the vehicle 100. The freewheeling reverse cog 310 allows for forward motion of the vehicle 100 while the reverse drive assembly is engaged. Other types of reverse drive mechanisms are contemplated.

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With renewed reference to FIG. 1, and in one embodiment, the vehicle 100 includes individual braking controls. A first front brake lever 350 controls one or both of the front brakes 355 attached to the front forks 130 for braking the front drive wheel assemblies 110 and a second brake lever 360 may control either a front brake 355 or a rear brake 365 which is attached to the rear wheel assembly 120. In one embodiment, front brakes 355 are linear side pull or center pull brakes positioned on the forks 130 to come into contact with each front rim 145 when activated by a front brake lever 350, 360. In another embodiment, the front brakes are hub brakes. In one embodiment, the rear brake 365 is a mechanical disc brake mounted to the rear hub of the rear wheel 120. The vehicle 100 includes a parking brake (not shown), which may be a lockable detent pin within a front brake lever 350, 360 for locking one or more wheels. In such embodiments, the parking brake retains the vehicle 100 in a stationary position during transfers, mounting or dismounting.

The activation mechanisms linking the first and second brake levers 350, 360 and the front brakes and rear brakes 355, 365, can include, for example, stainless steel cables with or without a lined housing, hydraulic lines or compressed air. Other braking systems suited to accommodate a rider's abilities and the vehicle application, including the full range of handactivated braking mechanisms designed for bicycles and motorcycles in various combinations with the activation mechanisms are contemplated.

Referring now to FIGS. 14 through 18, in one embodiment, the vehicle 100 includes two independent hand-operable cranks 250a and 250b, operably connected to a corresponding front drive wheel assembly 110 for propulsion of the vehicle 100 in a forward and reverse direction.

Referring now to FIG 18, in one embodiment, the crank handle 265 is rotatably attached to the crank arm 260 which is mounted to the crank arm housing 385. A roller clutch 386 is pressed into the crank arm housing 385. The crank arm housing 385 is attached to the crank drive shaft 387 for rotation. The crank drive shaft 387 is attached to the crank drive shaft housing 388

for rotation. The crank drive shaft 387 is supported by two bearings an inboard bearing 389 and an outboard bearing 420 which are attached to the crank drive shaft housing 388.

The crank drive shaft housing 388 is attached to the upper end of the main drive shaft housing 390. Affixed to the crank drive shaft 387, in one embodiment, is a miter gear 391. This miter gear 391 engages a second miter gear 392 which is attached to the upper end of the main drive shaft 393. The main drive shaft 393 is housed within the main drive shaft housing 390. The main drive shaft 393 is held in place, for rotation, by an upper bearing 394 and a lower bearing 395, which are attached to the main drive shaft housing 390. The main drive shaft housing 390 is attached to the frame 105 by one or more mounting brackets 400.

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Attached to the lower end of the main drive shaft 393 is a miter gear 396. This miter gear is positioned in such a way as to engage a bevel gear 397 which is attached to the hub 398 of the front drive wheel assembly 110. The hub 398 is attached to a cantilevered axle 399 which is attached to the frame of the vehicle 105.

In one embodiment, there is a hand-retractable spring plunger 401 mounted on the crank arm housing 385. The hand-retractable spring plunger 401 can be positioned in either an engaged or a disengaged position. The hand-retractable spring plunger 401, when placed in the engaged position, slides into a detent hole 402 which is located on the crank drive shaft 387. The crank drive shaft 387 may have one or more detent holes 402. When placed in the disengaged position, the hand-retractable spring plunger 401 is fully retracted into the body of the crank arm housing 385, and no longer engages the detent hole in the crank drive shaft 387. Referring further to figure 18, the arrow 403 indicates the direction for disengaging the hand-retractable spring plunger 401. The arrow 404 indicates the direction for engaging the hand-retractable spring plunger 401. The hand-retractable spring plunger 401 is held in place in the disengaged position by the rider rotating the hand-retractable spring plunger 401 90 degrees into a locked position.

In operation, the rider rotates the hand crank 250 in a forward direction to propel the vehicle forward. This can be either a circular motion or a forward-and-back motion, both resulting in forward motion of the vehicle 100. This is accomplished when the hand-retractable spring plunger 401 is in the disengaged position. This position is referred to as "freewheeling" in bicycling terminology. In this position, in the case of traveling down a hill, the front drive wheel assemblies 110 rotate while the hand cranks 250 remain stationary.

With the hand-retractable spring plunger 401 in the engaged position, the crank drive assembly becomes a fixed drive. In this case, when the rider rotates the hand cranks 250 forward, the front wheels 110 turn forward. When the rider rotates the hand cranks 250 in reverse, the front drive wheel assemblies 110 move in a reverse direction. When the rider holds the hand cranks 250 stationary, the front wheels 110 will also remain stationary.

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In operation, the hand cranks 250 turn the crank drive shaft 387, which rotates the miter gear 391 and miter gear 392. This rotates the main drive shaft 393 which rotates the lower miter gear 396 and the hub bevel gear 397. This accomplishes the rotation of the front drive wheel assembly 110 in a forward or reverse direction.

Specifically, with the hand-retractable spring plunger 401 in the disengaged position, the forward motion of the hand crank 250 causes the roller clutch 386 to engage the crank drive shaft 387. When the hand crank 250 is rotated in a reverse direction or remains stationary while the vehicle is in a forward motion, the roller clutch 386 will disengage the hand crank 250 from the crank drive shaft 387.

With the hand-retractable spring plunger 401 in the engaged position, the hand crank 250 is positively engaged with the crank drive shaft 387. In this instance, either forward or reverse rotation of the hand crank 250 will result in a corresponding forward or reverse rotation of the front wheel assembly 110.

In another embodiment, the miter gear 396 at the lower end of the main drive shaft 393 engages a modified coaster brake hub (not shown), such as the Sram internal gear hub with coaster brake which is a standard component within the bicycling industry. This Sram hub is modified by a kit available from a bicycle specialty company, Van Raam Aalten B.V. (the Netherlands).

In operation, the Van Raam-modified Sram hub allows the rider to pedal forward for forward motion, freewheel in forward motion, and pedal in reverse for reverse motion. In the case of this embodiment, the roller clutch 386 and the spring loaded plunger 401 are excluded.

In another embodiment, the inventors contemplate an adaptive feature which allows the rider to propel the vehicle using a lever-drive motion instead of a circular hand-crank motion (not shown). This would be accomplished by removing one or more of the crank handles 265 and replacing it with a specially fitted lever. This lever adaptation kit would include 2 adjustable

stops which would determine the range of the lever's extension and retraction according to what is ideal for each individual (not shown).

A number of embodiments have been described. Nevertheless, it will be understood that various modifications may be made without departing from the spirit and scope of the invention. Accordingly, other embodiments are within the scope of the following claims. For example, for rehabilitative applications, the vehicle can include a foot pedal assembly (not shown) configured as in a conventional bicycle foot crank mechanism to which the rider's feet can be positioned. In one embodiment, at least one of the hand crank sprockets 255 and the foot pedal assembly are operably connected by a direct drive arrangement. In this configuration, the drive chain 275 attached to the crank sprockets 255 provides propulsion of the vehicle 100 and simultaneously rotates the foot pedals, allowing improved circulation to and neuro-stimulation of the lower limbs.

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The foregoing embodiments are therefore to be considered in all respects illustrative rather than limiting of the invention described herein. The scope of the invention is thus indicated by the appended claims rather than by the foregoing description, and all changes which come within the meaning and range of equivalency of the claims are therefore intended to be embraced herein.

WHAT IS CLAIMED IS:

- 1 1. A human-powered vehicle (100) comprising:
- 2 a structural frame (105);
- two front wheels (110) mounted to fixed axles at a forward portion of the frame (105) for rotation;
- a seat (115) secured to the frame, the seat positioned between the front wheels (110) and adapted to pivot about a seat pivot axis; and
- a steerable rear wheel (120) mounted to the frame (105) behind the seat (115) and defining a rear wheel kingpin axis, the rear wheel (120) operably linked to the seat (115) such that pivoting of the seat (115) about the seat pivot axis causes pivoting the rear wheel (120) about the kingpin axis to steer the vehicle (100).
- 1 2. The vehicle of claim 1 wherein the seat pivot axis is substantially vertical.
- 1 3. The vehicle of claim 1 wherein the seat pivot axis is declined toward the front wheels 2 (110) to define a declination angle.
- 1 4. The vehicle of claim 3 wherein the declination angle is between about 25 and 75 degrees.
- 1 5. The vehicle of claim 3 wherein the declination angle is about 45 degrees.
- 1 6. The vehicle of any of claims 3 to 5 wherein the seat (115) has an upper seating
- surface, the pivot axis intersecting the upper seating surface.
- The vehicle of any of the above claims wherein at least one of the two front
- wheels(110) is operably connected to a hand-operable crank (250) for propulsion of the
- 3 vehicle (100).
- 1 8. The vehicle of any of the above claims further comprising two independent hand-
- operable cranks (250), each crank operably connected to a corresponding front wheel (110).
- 1 9. The vehicle of any of the above claims further comprising at least one reverse drive
- 2 (300) for rearward propulsion of the vehicle (100).

- 1 10. The vehicle of any of the above claims wherein the hand-operable cranks (250) are
- adapted to be rotatable about substantially horizontal axes disposed above the front wheels
- 3 (110).
- 1 11. The vehicle of claim 10 wherein the hand-operable cranks (250) comprise crank
- sprockets (255) and the front wheels (110) include wheel sprockets (270), the crank sprockets
- 3 (255) being coupled to the wheel sprockets (270) by means for positive engagement.
- 1 12. The vehicle of any of claims 3 to 11 wherein a chain (215) is trained around a driven
- sprocket (180) secured to the rear wheel steering assembly (120), the chain (215) attached
- directly to first and second portions of the seat (115) by first and second cables (220), the
- chain (215) being crossed between the driven sprocket (180) and the first and second portions
- 5 of the seat (115).
- 1 13. The vehicle of claim 12 wherein the chain (215) is adjustably attached to at least one
- of the first and second cables (220).
- 1 14. The vehicle of claim 12 further comprising first and second guides to redirect the
- cables (220) from a substantially horizontal orientation to a substantially vertical orientation.
- 1 15. The vehicle of any of the above claims wherein the seat (115) is operably connected
- to the rear wheel (120) by a flexible chain, roller chain or nylon belt.
- 1 16. The vehicle of claim 15 wherein the chain (185) is trained about a drive sprocket
- 2 (175) secured to the seat (115) and a driven sprocket (180) secured to the rear wheel steering
- assembly (120), the chain being crossed between the drive and the driven sprockets.
- 1 17. The vehicle of claim 16 wherein the drive sprocket (175) is disposed on a seat
- support shaft allowing alignment of the rear wheel relative to the seat position.
- 1 18. The vehicle of any of the above claims further comprising an actuator (195)
- connecting the seat and the structural frame and biasing the seat toward a neutral pivot
- 3 position.

- 1 19. The vehicle of claim 18 wherein the bias of the actuator (195) is adjustable by the
- 2 user.
- 1 20. The vehicle of claim 18 or 19 wherein the actuator (195) comprises a pressurized
- 2 cylinder.
- 1 21. The vehicle of claim 19 wherein the actuator (195) comprises a spring.
- 1 22. The vehicle of any of the above claims wherein a steering damper (197) is connected
- 2 to the rear wheel steering assembly (120) and the structural frame (105).
- 1 23. The vehicle of any of the above claims further comprising independent and hand-
- operable front brakes (355) and rear brakes (365).
- 1 24. The vehicle of any of the above claims wherein the structural frame (105) further
- comprises an adjustable footrest (128) positioned between the front wheels (110).
- 1 25. The vehicle of any of the above claims wherein the front wheels (110) are each
- 2 mounted for rotation about a respective axle secured to the frame (105) by a fork spanning
- 3 the wheel.
- 1 26. The vehicle of any of the above claims wherein the front wheels (110) are each
- 2 mounted for rotation about a cantilevered axle secured to the frame (105).
- 1 27. The vehicle of any of the above claims wherein the front wheels (110) are slanted
- 2 toward each other to define a positive camber angle with respect to vertical.
- The vehicle of any of the above claims wherein the camber angle is between about 1
- 2 and 10 degrees.

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- 1 29. The vehicle of any of the above claims wherein the seat (115) is positioned such that
- the rear wheel (120) carries between about 20 and 40 percent of a total combined weight of
- the operator and the vehicle (100) when in a static condition.

- 1 30. A human-powered vehicle (100) comprising:
- a structural frame (105) supported on multiple road wheels including a driven wheel
- 3 rotatable (110) about an axle for propulsion;
- a seat (115) secured to the frame (105) for supporting an operator;
- a hand-operable crank (250) having a crank drive shaft 387 extending therefrom
- enclosed within a crank drive shaft housing (388), the hand-operable crank (250) being
- 7 disposed above the driven wheel (110) and rotatable by hand by an operator seated in the seat
- 8 (115); and
- a main drive shaft (393) enclosed within a main drive shaft housing (390) extending
- between the crank drive shaft housing (388) and the axle, the main drive shaft (393) operably
- connecting the crank drive shaft (387) and the driven wheel (110).
- 1 31. The vehicle of claim 30 further comprising a hand-retractable spring plunger (401)
- 2 and a roller clutch (386) disposed within the crank arm housing (385) for engaging and
- 3 disengaging the hand crank from the drive shaft (393).
- 1 32. The vehicle of claim 31 wherein the driven wheel (110) includes a coaster brake hub.
- 1 33. The vehicle of claim 31 wherein the vehicle is propelled by rotational motion of the
- 2 hand-operable crank (250).
- 1 34. The vehicle of claim 31 wherein the vehicle is propelled by a ratcheting motion of the
- 2 hand-operable crank (250).
- 1 35. The vehicle of claim 30 wherein the seat (115) is positioned between two front road
- wheels (110) and adapted to pivot about a seat pivot axis.
- 1 36. The vehicle of claim 35 wherein the driven wheel axle is mounted in a fixed
- 2 orientation to a forward portion of the frame (105).
- 1 37. The vehicle of claim 30 wherein the road wheels include two driven wheels (110),
- one on either side of the seat (115), and two independently operable hand cranks (250), each
- 3 hand crank operably connected to a respective one of the driven wheels (110) through a
- 4 respective crank drive shaft (387) and a respective main drive shaft (393).

- 1 38. The vehicle of claim 36 wherein the road wheels include a steerable rear wheel (120)
- 2 mounted to the frame (105) behind the seat and defining a rear wheel kingpin axis, the rear
- wheel (120) operably linked to the seat (115) such that pivoting of the seat about the seat
- 4 pivot axis causes pivoting the rear wheel (120) about the kingpin axis to steer the vehicle.
- 1 39. The vehicle of claim 38 wherein the seat pivot axis is substantially vertical.
- 1 40. The vehicle of claim 38 wherein the seat pivot axis is declined toward the driven
- wheels (110) to define a declination angle of between about 25 and 75 degrees.
- 1 41. The vehicle of claim 30 wherein the drive shaft (393) is coupled to the crank drive
- 2 shaft (387) by bevel gearing (391, 392).
- 1 42. The vehicle of claim 30 wherein the main drive shaft (393) is fully enclosed within
- 2 the main drive shaft housing (390).
- 1 43. The vehicle of claim 31 wherein the hand-retractable spring plunger (401) is
- 2 configured to propel the vehicle in a fixed forward drive mode.
- 1 44. The vehicle of claim 31 wherein hand-retractable spring plunger (401) is configured
- 2 to propel the vehicle in a fixed reverse drive mode.
- 1 45. The vehicle of claim 31 wherein the roller clutch (386) and the hand-retractable
- spring plunger (401) are configured to propel the vehicle in a free wheel forward drive mode.
- 1 46. The vehicle of claims 1 or 30 wherein the vehicle is configured to permit an operator
- 2 having the use of only one hand to both steer and propel the vehicle.

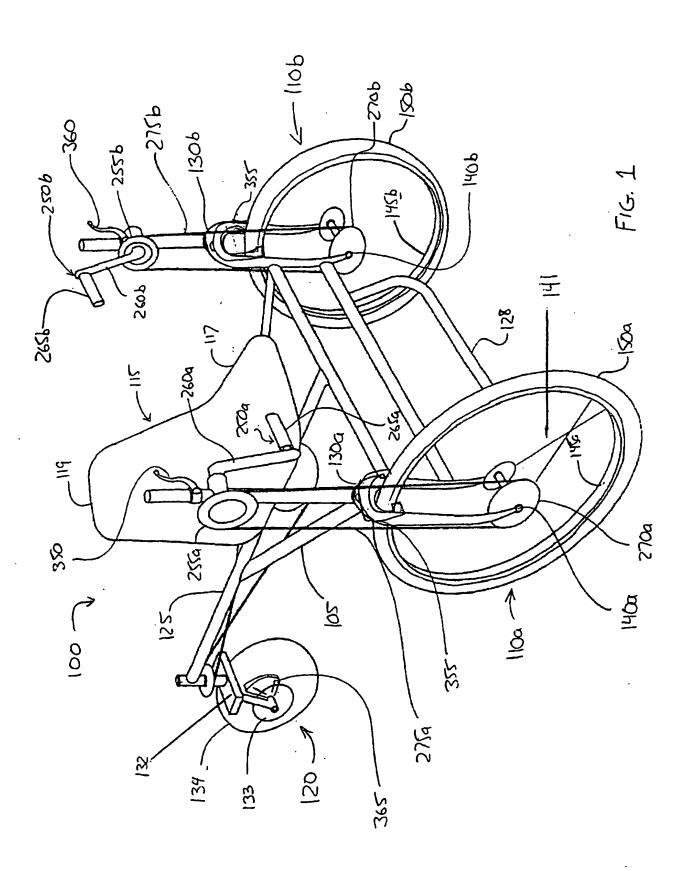
ABSTRACT

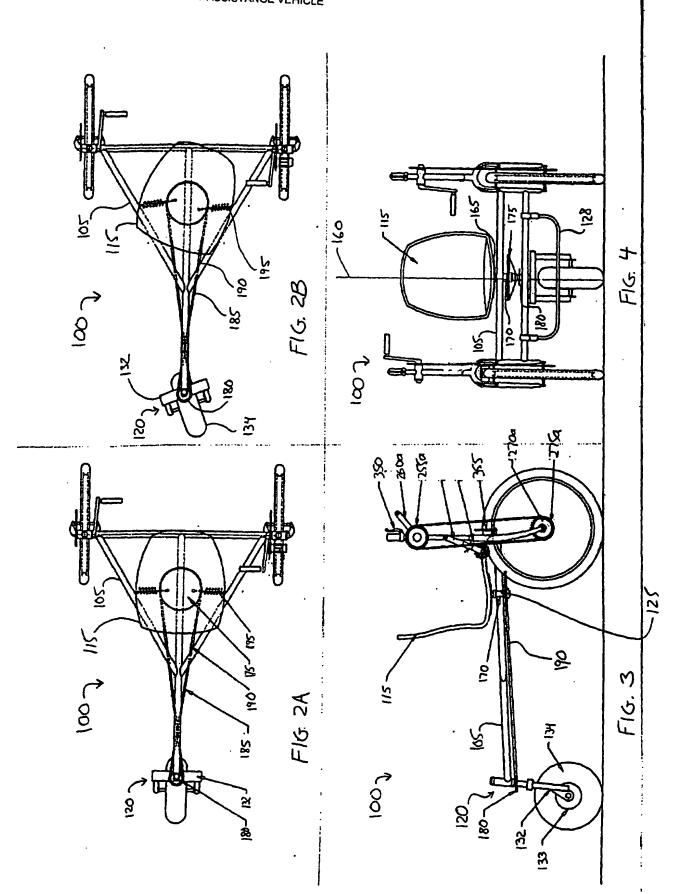
A human-powered vehicle (100) comprising a structural frame (105) supported on multiple road wheels including driven wheels (110) rotatable about an axle for propulsion, a seat (115) secured to the frame (105) for supporting an operator, a hand crank (250) disposed above the driven wheel (110) and rotatable by hand by an operator seated in the seat (115), and a main drive shaft (393) enclosed within a main drive shaft housing (390) and operably connecting a crank drive shaft (387) extending from the hand crank (250) and the driven wheel (110). A steerable rear wheel (120) can be operably linked to the seat (115) such that pivoting of the seat (115) about a seat pivot axis causes pivoting of the rear wheel (120) to steer the vehicle (100).

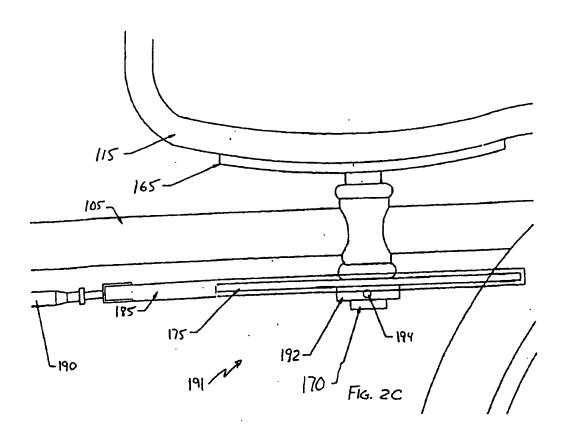
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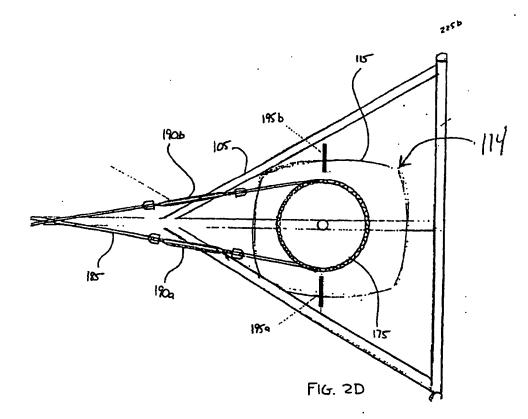
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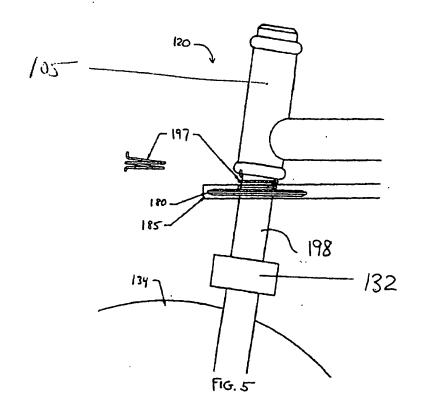
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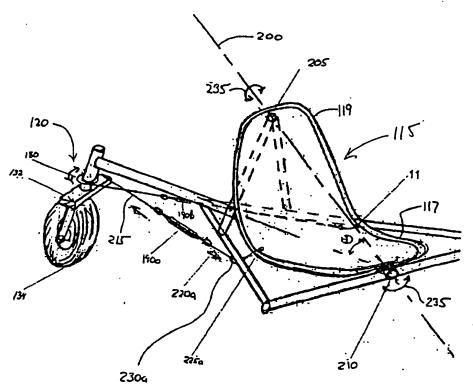
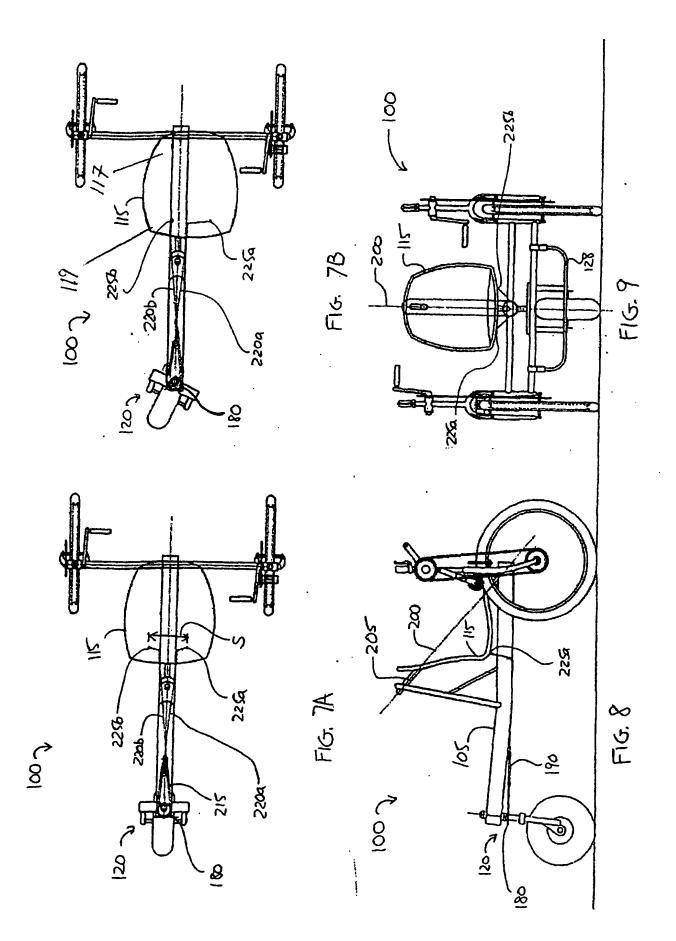
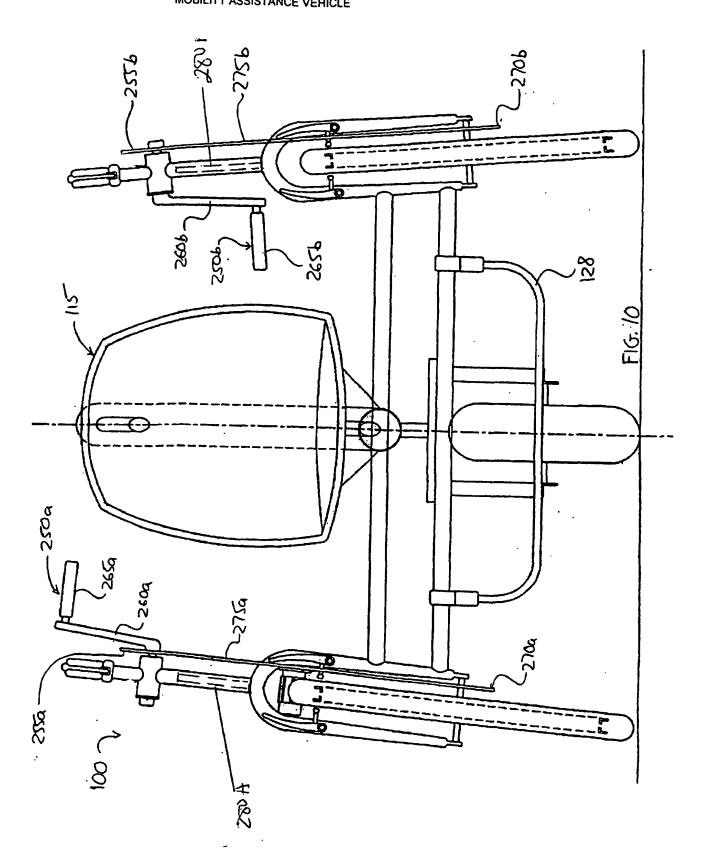
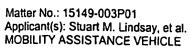
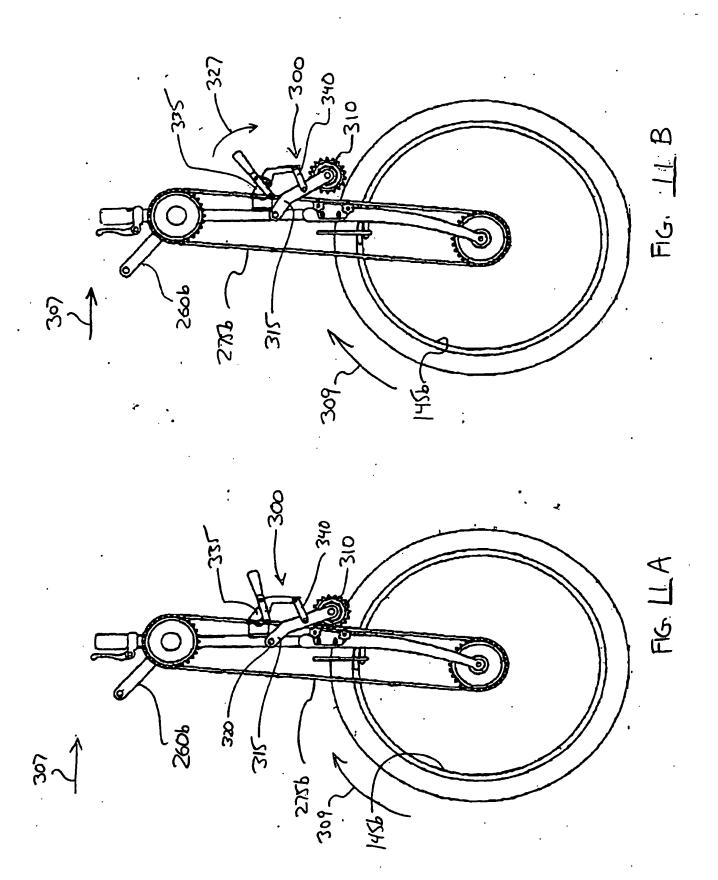


FIG. 6









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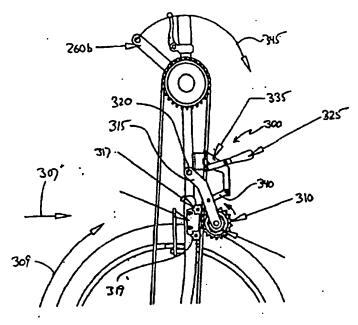
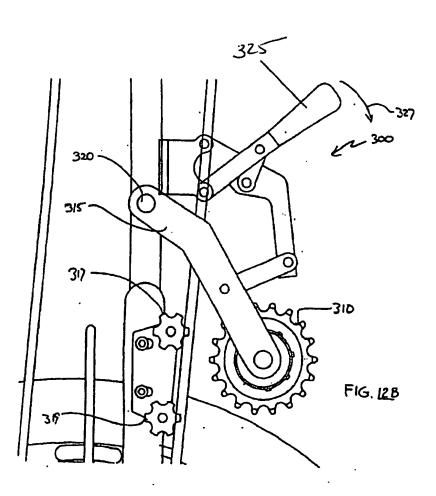


FIG. IZA



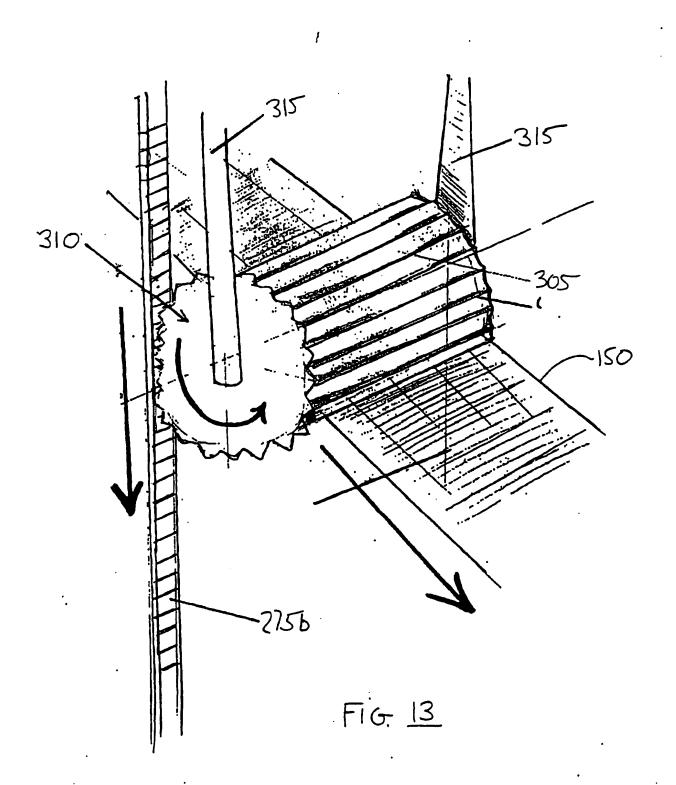
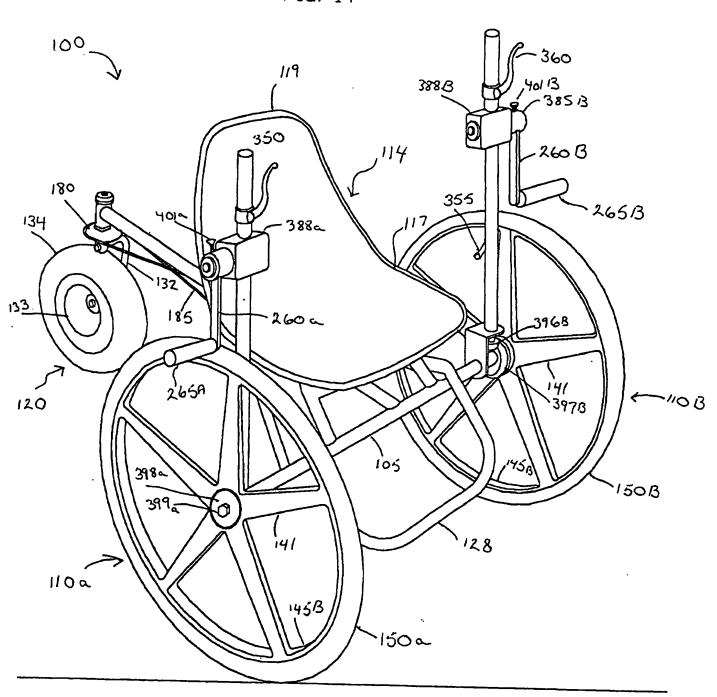
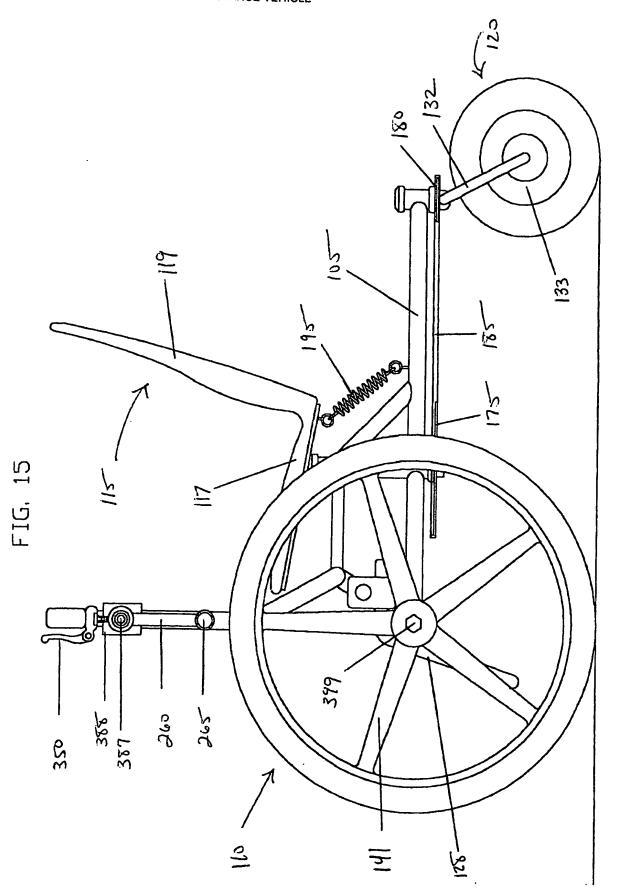


FIG. 14





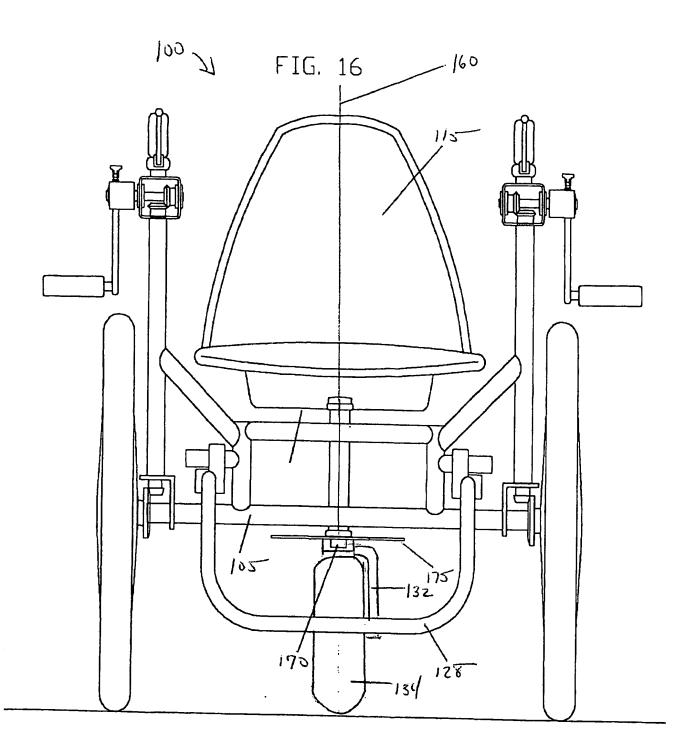
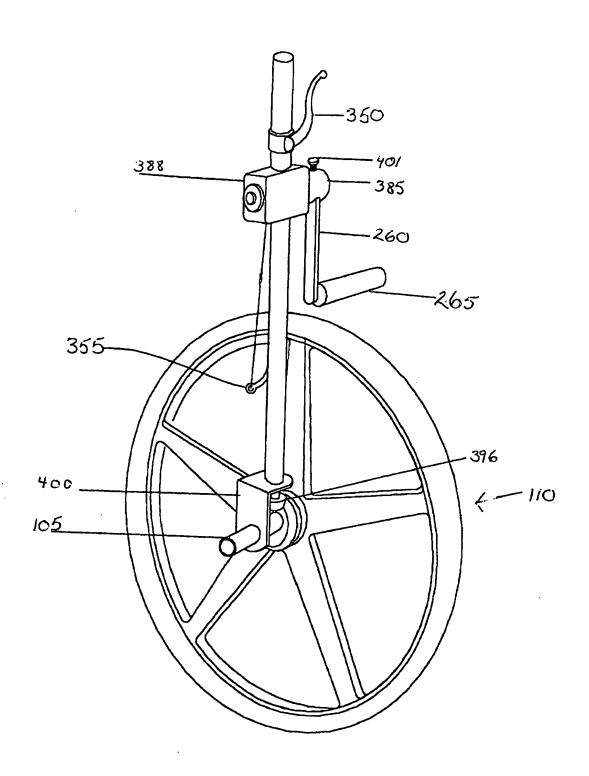
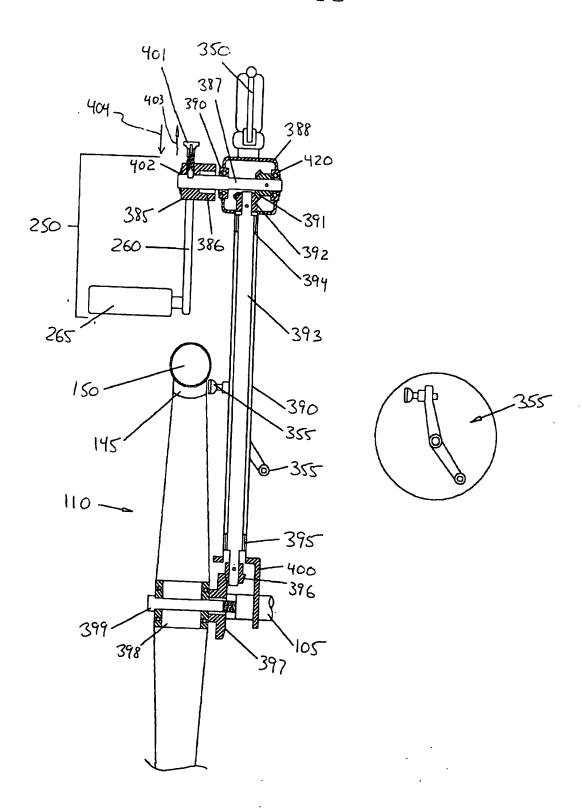


FIG. 17



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